

Performance of direct-drive cryogenic targets on OMEGA^{a)}

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The success of direct-drive-ignition target designs depends on two issues: the ability to maintain the main fuel adiabat at a low level and the control of the nonuniformity growth during the implosion. A series of experiments was performed on the OMEGA Laser System [T. R. Boehly, D. L. Brown, R. S. Craxton *et al.*, *Opt. Commun.* **133**, 495 (1997)] to study the physics of low-adiabat, high-compression cryogenic fuel assembly. Modeling these experiments requires an accurate account for all sources of shell heating, including shock heating and suprathreshold electron preheat. To increase calculation accuracy, a nonlocal heat-transport model was implemented in the 1D hydrocode. High-areal-density cryogenic fuel assembly with $\rho R > 200$ mg/cm² [T. C. Sangster, V. N. Goncharov, P. B. Radha *et al.*, “High-areal-density fuel assembly in direct-drive cryogenic implosions,” *Phys. Rev. Lett.* (submitted)] has been achieved on OMEGA in designs where the shock timing was optimized using the nonlocal treatment of the heat conduction and the suprathreshold-electron preheat generated by the two-plasmon-decay instability was mitigated.

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I. INTRODUCTION

In the inertial confinement fusion (ICF) approach to fusion, a spherical shell filled with a deuterium-tritium (DT) mixture is compressed to reach a temperature of 10–12 keV in a lower-density central core region (hot spot) to initiate a burn wave through the higher-density, colder main fuel surrounding the core.^{1–3} The main fuel areal density (ρR) at that time must be large enough to burn a significant fraction of the fuel.^{1,2} The peak areal density depends mainly on the fuel adiabat (defined as the ratio of the shell pressure to the Fermi-degenerate pressure at the shell density) and the laser energy,⁴

$$(\rho R)_{\max} = \frac{2.6}{\alpha^{0.54}} E_{\text{MJ}}^{1/3}. \quad (1)$$

To study the physics of low-adiabat, high-compression fuel assembly a series of experiments with cryogenic D₂ and DT fuel was designed and performed on OMEGA.⁵ Figure 1 summarizes the measured areal densities of cryogenic target implosions reported earlier.^{6,7} The targets used in these experiments were D₂-filled CD shells with the outer diameter

of ~ 860 μm , the shell thickness of 3–5 μm , and the cryogenic layer thickness between 92 and 98 μm . The targets were driven with shaped laser pulses at peak intensities of 6–10 $\times 10^{14}$ W/cm² to set the fuel adiabat at $\alpha = 2$ –25. Figure 1 compares the experimental areal density, $\langle \rho R \rangle_{\text{exp}}$, inferred from the energy loss of the secondary protons⁸ while they propagate through the compressed fuel and the simulated areal density, $\langle \rho R \rangle_{\text{1D}}$, averaged over the 1D neutron-production history calculated using the hydrocode LILAC.⁹ A constant flux-limiter thermal conduction model¹⁰ with $f = 0.06$ was used in these simulations. As seen in the figure, the experimental data significantly deviate from simulation results for the implosions with a mid-to-low designed adiabat when the predicted $\langle \rho R \rangle_{\text{1D}} > 100$ mg/cm². The goal of the study presented in this paper is to identify the main sources of the measured $\langle \rho R \rangle$ deviation from the theoretical predictions. Equation (1) is used for guidance in this study. According to this equation, the observed degradation in the areal density comes from an underestimation of the predicted adiabat.

In this paper we consider several sources for adiabat degradation during the implosion, including shock heating and the preheat due to suprathreshold electrons. Based on the results of this study, target designs were optimized using the

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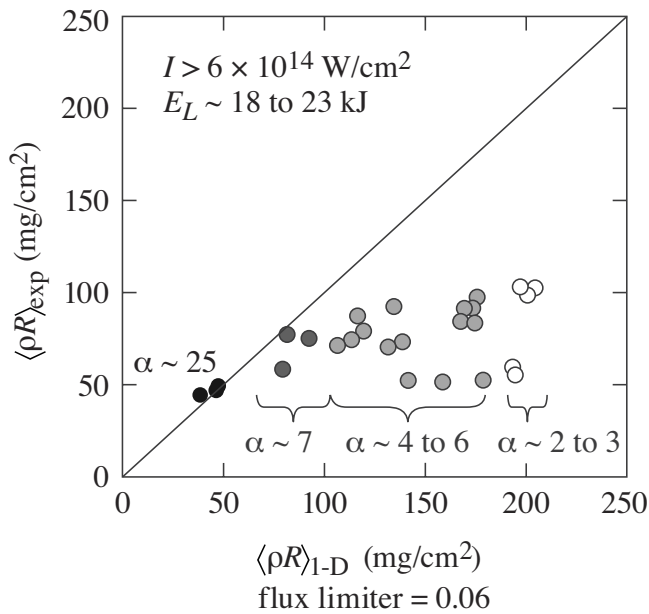


FIG. 1. Measured neutron-averaged areal density $\langle \rho R \rangle$ as a function of the simulated value using the hydrocode LILAC that uses a thermal conduction model with a constant flux-limiter $f=0.06$. The drive intensities were above $6 \times 10^{14} \text{ W/cm}^2$ and the laser energy varied from 18 to 23 kJ.

improved nonlocal thermal conduction model implemented in the 1D hydrodynamic code LILAC. High-areal-density cryogenic fuel assembly¹¹ with $\langle \rho R \rangle > 200 \text{ mg/cm}^2$ has been achieved on OMEGA using designs where the shock timing was optimized and the suprathermal-electron preheat generated by the two-plasmon-decay instability was mitigated. The paper is organized as follows: The modeling of the shock heating is described in Sec. II. Section III considers both the preheat effects due to the suprathermal electrons and the reduction in the measured areal density due to the burn truncation before the peak shell ρR is reached. The conclusions are presented in Sec. IV.

II. MODELING OF SHOCK HEATING

A typical laser pulse for a low-adiabat, direct-drive design consists of a lower-intensity foot (or, as shown in Fig. 2, a picket used in adiabat-shaping designs^{12,13} to mitigate the Rayleigh–Taylor instability growth¹⁴), a transition region, and the higher-intensity main pulse. At the beginning of the pulse, a shock wave (SW) is launched into the shell. Its strength determines the shell adiabat α . The compression wave (CW), initiated as the intensity rises during the transition region, must be properly timed to avoid an excessive adiabat increase at the inner part of the shell. Indeed, if the CW catches the SW too early in the shell, the SW strength increases, raising the adiabat. Delaying the CW, on the other hand, steepens up its front and turns the CW into a shock as the CW travels along the density gradient produced by the rarefaction wave (RW) that is formed after the SW breaks out at the inner surface of the cryogenic layer. To prevent an excessive reduction in the fuel areal density, the coalescence of the RW with the CW must occur within the last 10% of the main fuel mass, as observed in calculations. This condition limits the allowable mistiming of the shock breakout to

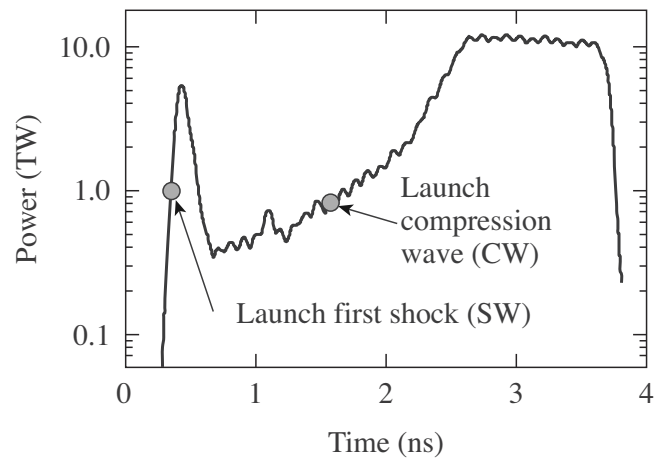


FIG. 2. A typical pulse shape for the OMEGA, direct-drive, low-adiabat design.

$\Delta t_s/t_s \leq 5\%$ and constrains the modeling accuracy in the absorbed laser energy E_s during the shock propagation. For a constant-intensity foot pulse, the shock-propagation time is $t_s = \Delta_0/U_s$, where $U_s \sim \sqrt{p_a}$ is the shock speed and Δ_0 is the initial shell thickness. The ablation pressure scales as $p_a \sim P^{2/3}$, where P is the laser power; and the laser energy can be written in the form $E_s \sim P t_s$. This gives $t_s \sim \Delta_0^{3/2} E_s^{-1/2}$. The same scaling can be obtained when the shock is launched by a narrow picket. The shock-breakout time in this case¹² is $t_s \sim (E_p^{-1/3} \Delta_0)^\beta$, where $\beta = [1 - \sqrt{2\gamma(\gamma-1)}/(2(2\gamma-1))]^{-1}$, γ is the ratio of specific heats, and t_p and E_p are the picket duration and energy, respectively. For $\gamma > 1.2$, the exponent is $\beta \approx 3/2$ with less than 10% error, leading to $t_s \sim E_p^{-1/2}$, similar to the case of a constant-intensity pulse. Using $\Delta t_s/t_s < 5\%$, the requirement for the modeling accuracy in the absorbed picket energy becomes $\Delta E_p/E_p < 10\%$.

Inverse bremsstrahlung is the main absorption mechanism for $\lambda = 0.351\text{-}\mu\text{m}$ -wavelength laser irradiation. The absorption fraction depends on the electron-temperature and electron-density profiles.¹⁵ These profiles, in turn, are determined by the thermal conduction near the location of the peak in the laser-energy deposition. Thermal conduction modeling is crucial, therefore, when calculating the laser-energy deposition. In addition to inverse bremsstrahlung, resonance absorption¹⁵ can be important at early times when the electron density at the critical surface is steep enough for the electric field to tunnel from the laser turning point to the critical density and excite plasma waves. The next two subsections study the contributions of resonance absorption and nonlocal electron transport on the laser absorption in ICF plasmas.

A. Resonance absorption modeling

The effect of resonance absorption was studied for direct-drive-relevant conditions using a numerical solution of the wave equations in planar geometry. The results of these calculations¹⁶ were used to develop a simplified analytical model that can be implemented into hydrodynamic codes to model spherical implosions. The model is based on the ap-

proach described in Ref. 15. We consider a p -polarized electromagnetic wave with incident angle θ between the direction of propagation and the density gradient, which points along the z direction. The z component of the electric field E_z tunnels through from the laser turning point to the critical density, depositing a fraction f_A of the incident laser energy into plasma waves (resonance absorption¹⁵). Propagating down the density gradient, the energy of these waves is damped into the electrons. Calculations show¹⁶ that the average temperature of the resonance electrons for $\lambda_L=0.351\text{-}\mu\text{m}$ -wavelength laser irradiation does not exceed ~ 5 keV. Resonance absorption, therefore, enhances the local absorption due to the inverse bremsstrahlung. Resonance absorption is calculated by evaluating the energy flux¹⁵ $I_{\text{abs}}=\int_0^\infty \nu E_z^2/8\pi dz$, where ν is the damping rate of the plasma waves. The main contribution to this integral comes near the resonance point, in the vicinity of the critical density, resulting in

$$I_{\text{abs}} = \frac{\omega L_n}{8} (\sin \theta B_{\text{cr}})^2, \quad (2)$$

where B_{cr} and L_n are the magnetic field and the density scale length at the critical density, respectively. The resonance field is calculated by multiplying the field amplitude at the turning point, $B_t=0.9E_0(c/\omega L_n)^{1/6}$, by a tunneling factor.¹⁵ Here, E_0 is the laser field in free space. In deriving B_t the laser-energy absorption in the region below critical density was neglected, leading to an overestimate in the resonance field. Correcting for this absorption and adding the intensities of the incoming and outgoing waves, $f_i E_0^2$ and $(f_i - f_A) E_0^2$, respectively, the magnetic field becomes $B_t=0.9\sqrt{2f_i - f_A} E_0(c/\omega L)^{1/6}/2$, where f_i is the fraction of the laser energy that reaches the turning point. Multiplying B_t by the tunneling factor $\exp(-\omega/c \int_{z_t}^{z_c} \sqrt{-\epsilon} dz)$, we obtain $f_A = \phi^2(2f_i - f_A)/8$ and

$$f_A = \frac{2f_i}{8/\phi^2 + 1}, \quad (3)$$

where $\phi = 2.3\tau \exp(-2\tau^3/3)$, $\tau = (3\omega/2c \int_{z_t}^{z_c} \sqrt{-\epsilon} dz)^{1/3}$, $\epsilon = 1 - n/n_{\text{cr}}$ is the dielectric function, n and n_{cr} are the electron density and the critical density, respectively; and z_t and z_c are the position of the turning point and critical density, respectively. Since the incident laser light in ICF experiments consists of a mixture of s and p polarizations, the resonance absorption fraction in a hydrocode simulation is taken as half value predicted by Eq. (3). Simulations show that Eq. (3) agrees very well with the results of more rigorous calculations.¹⁶

The tunneling factor depends on the density scale length at the critical surface. Thus, an accurate calculation of both inverse bremsstrahlung and resonance absorption relies on thermal transport modeling, which affects hydrodynamic profiles in the energy-deposition region. The next subsection discusses electron thermal transport in laser-produced plasmas.

B. Heat transport modeling

Because of the steep temperature and density profiles where the laser deposition is at a maximum, the validity of Spitzer thermal conduction¹⁷ breaks down (the mean free path of the heat-carrying electrons is comparable to or larger than the temperature scale length). In a model using flux limitation,¹⁰ the thermal flux is calculated as a fraction f of the free-stream flux $q_{\text{fs}} = nT v_T$ when the Spitzer heat flux $q_{\text{sp}} > f q_{\text{fs}}$. Here, $v_T = \sqrt{T/m}$ is the electron thermal velocity, and m , T , and n are the electron mass, temperature, and free-electron density, respectively. Since the flux-limiter value f cannot be determined directly from physical principles, its value, usually taken to be a constant in time, is obtained by comparing simulation results with experimental observables. Remarkably, such a simple model is able to successfully explain a large number of experiments with simple pulse shapes. However, for shaped, low-adiabat pulses, the flux limiter, as first shown in Fokker–Planck simulations,¹⁸ must be time dependent. The time dependence is especially important in simulating adiabat-shaping designs,^{12,13} where a narrow picket is introduced at the beginning of the laser pulse to tailor the shell adiabat and mitigate Rayleigh–Taylor instability growth.¹⁴ Accurate accounting of the absorbed picket energy as well as the laser coupling during the transition region (see Fig. 2) is crucial for the shock-timing calculation.

Since it is highly impractical to obtain the temporal shape of the flux limiter based only on the experimental data, a thermal-transport model must be developed for self-consistent flux calculations. Such a model was proposed in Ref. 19, where the simplified Boltzmann equation was solved using the Krook approximation.²⁰ The main disadvantage of such a model is the lack of particle and energy conservation because of the energy-dependent collisional frequency. Calculations show that, for the conditions relevant to ICF experiments, the error in calculating the local electron density and energy using the solution of the model described in Ref. 19 does not exceed 5%. Despite the fact that the error is small, the model used in the present calculations has been modified to recover the conservation properties. This is accomplished by renormalizing the local density and temperature used in evaluating the symmetric part of the electron distribution function. Similar modifications appear in the classical limit when the ratio of the electron mean-free path λ_{ei} to the temperature scale-length L_T is small.²¹ The second-order deviations from the Maxwellian f_M , $f_{\text{sym}} = f_M + f_n + v^2 f_T$, where $f_{n,T} \sim O[(\lambda_{\text{ei}}/L_T)^2]$, are due in such a limit to the contribution from the electron–electron collisions.²¹ These corrections are equivalent to the renormalization in the electron density and temperature used in the local Maxwellian distribution, $f_{\text{sym}} = f_M(n', T')$. Next, we describe the renormalization procedure used in the present nonlocal model.

The Boltzmann equation with the Krook collisional operator,²⁰

$$v_x \partial_x f + (eE/m) \partial_v f = -\nu_{ei}(v)(f - f_0),$$

can be solved analytically by substituting f_0 into the second term of the left-hand side,¹⁹

$$f = f_0 - \int^x G(x', v) e^{\xi/y} d\xi, \quad G = \lambda_{ei}(x') \left(\frac{\partial f_0}{\partial x} + \frac{eE_x}{T} \frac{\partial f_0}{\partial \epsilon} \right), \tag{4}$$

where $\xi(x') = \int_x^{x'} dx'' / \lambda_{ei}(x'')$, $\epsilon = mv^2/2T$, $y = \cos \theta$, $\lambda_{ei} = v / \nu_{ei}$, $\nu_{ei} \sim v^{-3}$ is the electron-ion collisional frequency, and E_x is the slowly varying electric field. Assuming that f_0 is a function of the renormalized density n' and temperature T' , the relations between (n', T') and (n, T) are found by integrating Eq. (4), multiplied by 1 and $mv^2/2$, yielding $n = n' - R_1$ and $3nT/2 = 3n'T'/2 - R_2$, respectively, where $R_1 = 2\pi \int_0^\infty dv v^2 \int_0^1 dy (H_L - H_R)$, $R_2 = \pi m \int_0^\infty dv v^4 \int_0^1 dy (H_L - H_R)$, $H_L = \int_{x_L}^x G e^{\xi/y} d\xi$, and $H_R = \int_x^{x_R} G e^{-\xi/y} d\xi$. The integration limits are defined as $\int_x^{\{x_R, x_L\}} dx'' / \lambda_{ei} = \{+, -\} \infty$. The electric current and the heat flux are calculated using the standard definitions, $j_x = e \int d^3v v_x f$ and $q_x = m \int d^3v v v_x^2 f / 2$. The electric field E_x is defined by the zero-current condition $j_x = 0$. This condition yields an integral equation for E_x , which is solved by the iteration method.¹⁹ For the distribution function f_0 , we use the Maxwellian function with the corrections due to the laser field²² $f_0 = f_M \exp(-0.07 \alpha_L \epsilon^{5/2})$, where $\alpha_L = Z v_e^2 / v_T^2$, Z is the average ion charge, and v_e and $v_T = \sqrt{T/m}$ are the electron quiver and thermal velocities, respectively.

Two main effects are introduced by the nonlocal treatment of the thermal transport: First, the flux is reduced from the Spitzer value in the regions with steep temperature gradients; and second, the main fuel is heated by the long-range electrons from the hotter plasma corona. The heat flux calculated using the distribution function in Eq. (4) does not correctly reproduce the nonlocal heating because the integrand in Eq. (4) does not go to zero at $\int_x^{x'} dx'' / \lambda_E = 1$, where λ_E is the electron-deposition range. Since the calculations must accurately account for every preheat source, it is essential to include a deposition cutoff. In the previous version of the nonlocal model,¹⁹ this was accomplished by replacing the exponential kernel $e^{\xi/y}$ in Eq. (4) with $\sqrt{1 - \xi/y}$. Such a substitution, however, does not properly recover the Spitzer limit. In the current version of the model, a test-particle approximation is used in evaluating λ_{ei} to produce the deposition cutoff. This approach gives Spitzer conductivity when $\lambda_{ei} / L_T \ll 1$. In the test-particle approximation, λ_{ei} is calculated along the particle trajectory using the energy-loss equation $dK/ds = -K/2\lambda_E$. Since $\lambda_E \sim K^2$, we obtain $K = K_0 \sqrt{1 - \int_x^{x'} dx'' / y \lambda_E}$, where $ds = dx/y$ is a path element. Then, the deposition cutoff is introduced in Eq. (4) by replacing $\lambda_{ei}(x')$ with $\lambda_{ei}(x', x) = \lambda_{ei}(x') (1 - \int_x^{x'} dx'' / y \lambda_E)$.

Next, we compare the results obtained using the described nonlocal model with simulations based on flux-limited Spitzer conduction. Figure 3 shows the effective flux limiter (defined as the maximum ratio of the nonlocal heat flux to the free-stream flux q_{fs} in the vicinity of maximum q_{sp} in the plasma corona) as a function of time for an $\alpha=2$ cryogenic implosion. The higher value of the flux limiter during the picket indicates a larger predicted laser absorption

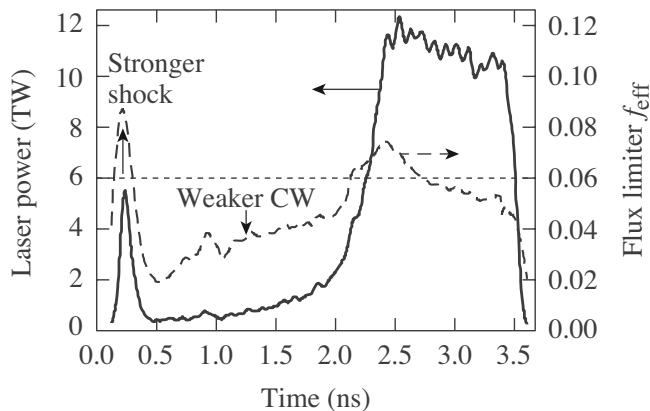


FIG. 3. Laser pulse (solid line, left axis) and the effective flux limiter f_{eff} (dashed line, right axis) obtained using the nonlocal model for an $\alpha=2$ cryogenic OMEGA design with 95- μm -thick D_2 ice layer and 10- μm -thick CD overcoat. The thin dashed line shows the standard value of the flux limiter used in the hydrocode LILAC.

and a stronger SW relative to calculations based on the constant flux-limiter model with $f=0.06$. Then, as the laser intensity relaxes after the picket, the effective flux limiter takes on a reduced value, leading to a weaker CW. If these effects are not properly modeled in a simulation, they lead to a significant shock mistiming and areal-density reduction.

To test the accuracy of the absorption calculations with the nonlocal transport model, the simulation results were compared with experimental absorption data²³ for implosions of 20- μm -thick plastic shells driven with a 200-ps Gaussian pulse at peak intensities varying from 5×10^{13} to 1.5×10^{15} W/cm^2 . Figure 4 shows the laser absorption fraction calculated using the flux-limited transport model with $f=0.06$ and no resonance absorption (empty squares), the flux-limited model with resonance absorption (solid squares), and the nonlocal model with resonance absorption (triangles). The resonance absorption effects are small when the

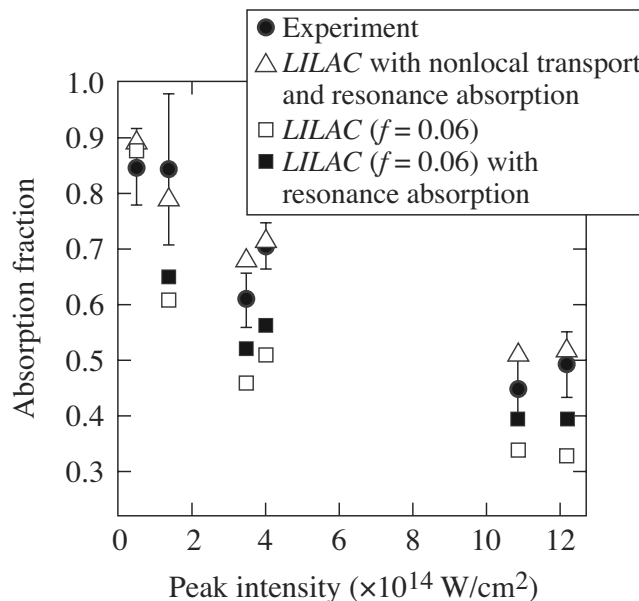


FIG. 4. Absorption fraction of the incident laser energy for a 20- μm -thick CH shell driven by a 200-ps Gaussian pulse at different peak intensities.

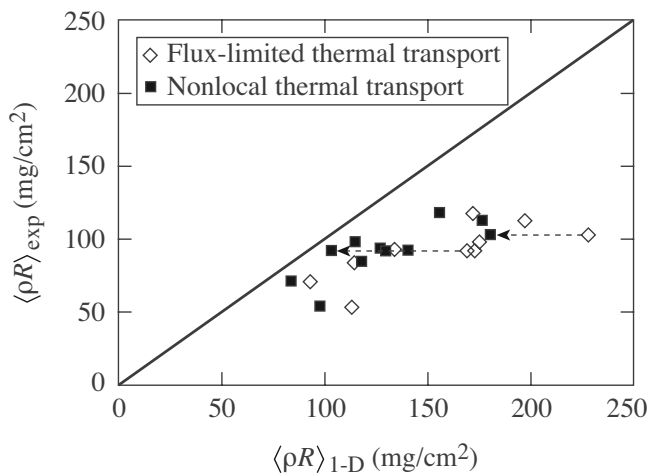


FIG. 5. Measured $\langle \rho R \rangle$ in the thin-CD cryogenic shell as a function of the simulated value using the hydrocode LILAC with a constant flux limiter $f=0.06$ (diamonds) and the nonlocal (squares) thermal conduction models. Arrows indicate reduction in the calculated areal density when the nonlocal model is used.

nonlocal thermal-transport model is used. These results, therefore, are not shown in Fig. 4. The flux-limited transport model produces much steeper electron-density profiles near the laser turning point, resulting in larger resonance absorption in comparison with the nonlocal model calculations. However, even with resonance absorption taken into account, the flux-limiter model underestimates the laser absorption fraction for most of the cases shown in Fig. 4. The nonlocal model, on the other hand, reproduces the experimental results very well. The nonmonotonic behavior of the absorption fraction with peak intensity is due to shot-to-shot variations in the picket width and the rate of intensity rise.

Next, the areal densities for the cryogenic implosions shown in Fig. 1 were recalculated using the nonlocal thermal-transport model. The data are plotted in Fig. 5. The improved agreement with the experimental data is due to a reduction in the calculated areal density resulting from significant shock mistiming predicted by the nonlocal model (see arrows in Fig. 5 showing this reduction for individual shots). Even though the calculations with the nonlocal model are in better agreement with the experimental data, some discrepancy still remains. In the next section we examine possible sources for the remaining discrepancy, starting with suprathermal-electron preheat.

III. SUPRATHERMAL-ELECTRON PREHEAT AND ρR SAMPLING

Several laser-plasma interaction processes are capable of generating suprathermal electrons in the plasma corona. As discussed in the Introduction, the degradation in ρR is significant if the adiabat at the inner part of the shell is increased. The electron preheat is important, therefore, if the electron-deposition ranges exceed the thickness of the cold part of the shell during the implosion. Thus, for the OMEGA designs, only electrons with energy in excess of 50 keV can reduce the peak shell compression. To estimate the amount of energy deposited in the shell required to degrade the

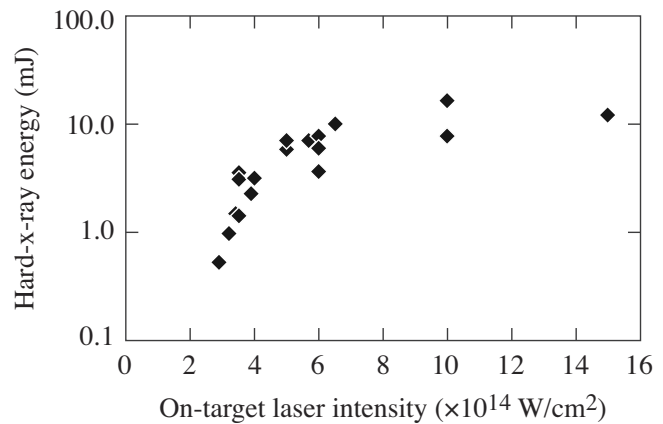


FIG. 6. Measured bremsstrahlung radiation above 40 keV for the thin CD-shell cryogenic implosions. The inferred hard-x-ray temperature in these implosions is above 50 keV.

fuel areal density, we use the pressure-density relation¹ $p \sim \alpha \rho^{5/3}$ and assume the ideal gas equation of state. This gives $\alpha \sim T^{5/3}/\rho^{2/3}$. The shell pressure is proportional to the ablation pressure p_a , which is determined by the laser intensity. Hence, for a given drive intensity, according to Eq. (1), $\rho R = (\rho R)_0 / (T/T_0)^{0.9}$, where $(\rho R)_0$ and T_0 are the areal density and electron temperature without the effects of preheat. The shell temperature during the acceleration phase in a typical low-adiabat design is ~ 20 eV. A 20% reduction in the areal density corresponds to a 6-eV increase in the shell temperature. For an OMEGA target this leads to ~ 10 J of preheat energy deposited into the unablated part of the shell. The lowest-threshold mechanism capable of producing energetic electrons with $T_{\text{hot}} > 50$ keV is the two-plasmon-decay instability.¹⁵ The threshold parameter η for this instability²⁴ is

$$\eta = \frac{I_{14} L_n (\mu\text{m})}{230 T_{\text{keV}}} \frac{\lambda_L}{0.351 \mu\text{m}}, \quad (5)$$

where I_{14} is the laser intensity in units of 10^{14} W/cm², L_n is the density scale length, and λ_L is the laser wavelength. The instability develops when $\eta > 1$. For a typical OMEGA implosion, $L_n \sim 150 \mu\text{m}$ and $T_{\text{keV}} \sim 1$ at $I_{14} \sim 1$. Thus, the instability is expected to develop when the drive intensity exceeds a few 10^{14} W/cm².

The experimental signature of the suprathermal-electron preheat is the measured hard-x-ray signal.²⁵ This correlates with the $3\omega/2$ signal,²³ indicating that the two-plasmon-decay instability is the main mechanism producing the suprathermal electrons. The hard-x-ray signal above 40 keV measured in cryogenic implosions with 95- μm -thick D₂ layers and 3–5- μm -thick CD overcoat, shown in Fig. 6, increases with the laser intensity.²⁶ Taking this result into account, the peak drive intensity was reduced to below 3×10^{14} W/cm² to minimize the suprathermal-electron-preheat effect on the target performance.²⁶ The measured and predicted areal densities, together with data for $I > 5 \times 10^{14}$ W/cm², are plotted in Fig. 7. The improved agreement observed for the lower-intensity shots suggests

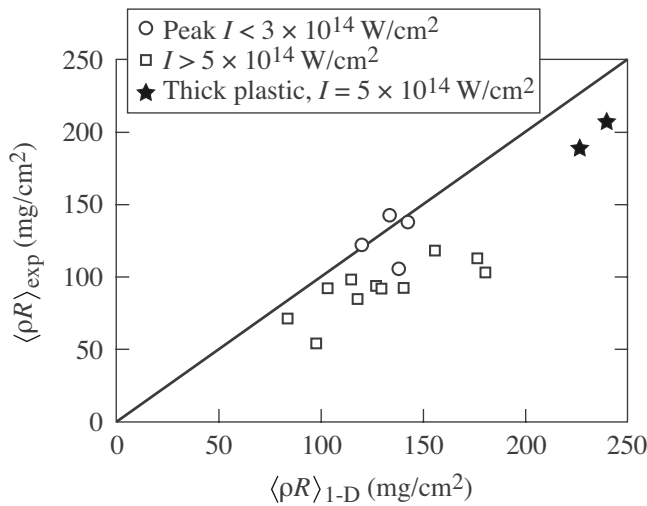


FIG. 7. Measured $\langle \rho R \rangle$ as a function of the simulated value using the hydrocode LILAC with the nonlocal transport model for cryogenic implosions at peak intensities $I > 5 \times 10^{14}$ W/cm² (squares) and $I < 3 \times 10^{14}$ W/cm² (circles), and for a 10- μ m-thick CD shell at $I = 5 \times 10^{14}$ W/cm² (stars).

that suprathreshold-electron preheat contributes to a modest degradation in ρR at higher drive intensities.

As the next step, the peak drive intensity was raised to 5×10^{14} W/cm² and the CD overcoat thickness was increased from 5 to 10 μ m. The thicker plastic shell was used to prevent the laser burning through the plastic to the deuterium during the target implosion and thus mitigate the suprathreshold-electron preheat at higher intensity. If the higher-Z plastic burns through during the pulse, as in the case of a 5- μ m-thick shell, lower-Z D₂ penetrates into the subcritical-density region, reducing the laser absorption. This, in turn, leads to a drop in the coronal temperature and an increase in the laser intensity at the quarter-critical surface. All of these factors raise the value of η , exciting the two-plasmon-decay instability at the time when the CD layer burns through. Increasing the CD overcoat thickness to 10 μ m allowed the drive intensity to be raised to 5×10^{14} W/cm². This produced a significantly smaller hard-x-ray signal compared to the thinner plastic shell, indicating lower suprathreshold preheat. The stars in Fig. 7 show the high areal densities (up to 202 ± 7 mg/cm²) achieved in these implosions, which are described in greater length in Ref. 11. Despite the small hard-x-ray signal, the measured areal densities were lower than the 1D prediction, indicating that additional mechanisms could be responsible for the deviation of $\langle \rho R \rangle_{\text{exp}}$ from the predicted value.

The areal density in the experiment is inferred from the energy downshift in the secondary protons created in the D³He reaction.⁸ The experimentally inferred $\langle \rho R \rangle$, therefore, is affected by the timing of the production of these protons with respect to the ρR temporal evolution. Figure 8(a) shows the experimental and predicted neutron-production histories for a cryogenic implosion with a 10- μ m-thick CD overcoat that yielded the highest $\langle \rho R \rangle_{\text{exp}}$. The predicted areal density history is plotted on the same figure. The figure shows that the experimental neutron-production rate is significantly reduced (presumably by perturbation growth during shell de-

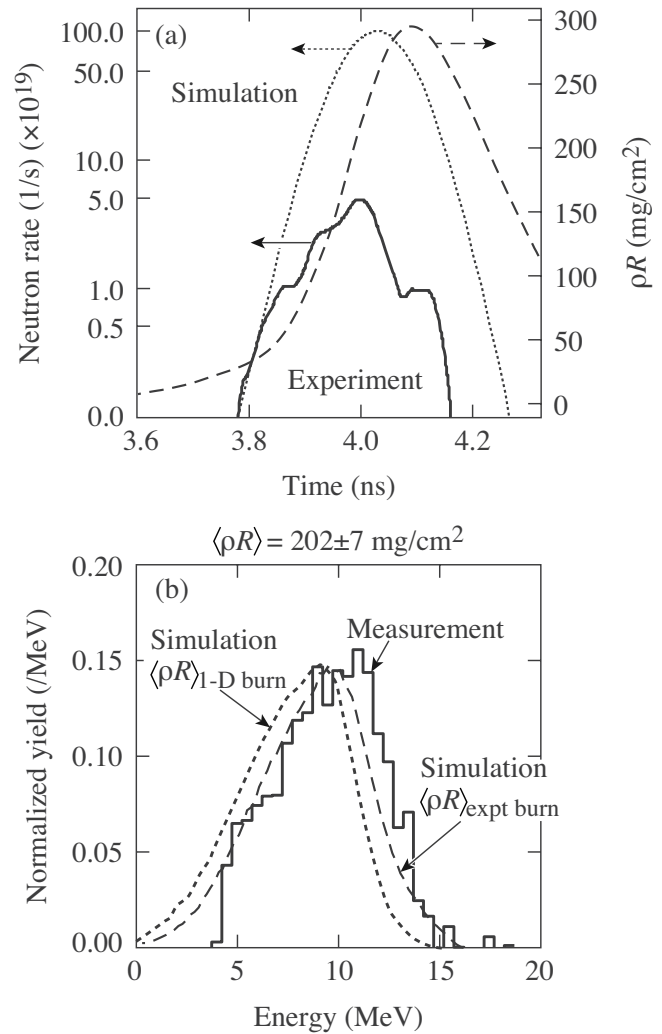


FIG. 8. (a) The neutron-production history measured (solid line) and predicted (dotted line). Also shown is the ρR evolution calculated with the 1D code LILAC (dashed line, right axis). (b) Measured secondary-proton spectrum (solid line) for a 10- μ m-thick CD shell with a 95- μ m-thick D₂ cryogenic layer driven on an $\alpha=2$ adiabat at $I = 5 \times 10^{14}$ W/cm². The dotted line shows the calculated spectrum averaged over the predicted 1D neutron production, and the dashed line represents the calculated spectrum averaged over the experimental neutron-production history.

celeration) at the time when the shell ρR reaches its peak value.²⁷ This could explain the lower measured areal density with respect to the results of 1D calculations [compare solid (measurement) and dotted (calculation) curves in Fig. 8(a)]. To address the sampling issue, Fig. 8(b) plots the predicted D³He proton spectrum averaged over the experimental neutron-production history (dashed curve), showing good agreement with the measured spectrum (solid curve) averaged over five individual measurements at different views of the implosion.

The suprathreshold-electron-generation efficiency for the NIF-scaled targets, not fully understood at present time, is currently under investigation. Preliminary experiments have been carried out to study preheat mitigation by doping the outer layer of the ablator with high-Z elements. In these experiments, warm plastic shells filled with 15 atm of D₂ gas were imploded using two pulse shapes to set the shell adiabat to $\alpha=2$ and 3, respectively. The outer 3–10 μ m of the shell

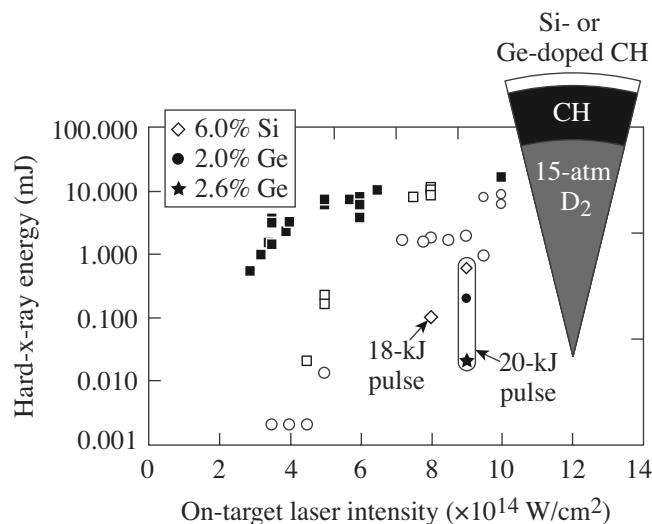


FIG. 9. Measured bremsstrahlung radiation above 40 keV for implosions with warm plastic (empty circles), doped plastic (diamonds, solid circle, and star), cryogenic 5- μm -thick CD (solid squares), and cryogenic 10- μm -thick CD (empty squares) shells.

were doped with 6%/atom of Si or 2% to 2.6%/atom of Ge. The total shell thickness was 27 μm . The increased laser absorption caused by the higher averaged ion charge in the plasma corona is predicted to raise the threshold for the two-plasmon-decay instability [see Eq. (5)], reducing the suprathermal-electron preheat. Figure 9 shows the hard-x-ray signal measured in pure-CH and CH shells doped with Si or Ge. The observed significant reduction in the signal level confirms the lower preheat level in the doped ablators. For comparison, Fig. 9 also shows the signal for cryogenic targets with 5- and 10- μm -thick CD shells.

In addition to the reduction in the hard-x-ray signal, the shells with Si-doped layers show improved hydrodynamic stability. The radiation from the higher-Z dopant preheats the shell, reducing both the initial imprint levels^{28,29} and the Rayleigh–Taylor instability growth. The improved stability of Si-doped shells with respect to the pure-CH shells results in an increase in both the experimental yields and the ratio of the experimental to the predicted yield. The latter is shown in Fig. 10. The increased yield is especially pronounced in the more unstable, $\alpha=2$ implosions when the thickness of the doped layer is 3 μm or greater. The stabilizing property of the high-Z dopants will be used in future OMEGA cryogenic designs. Calculations show that the radiation from the dopant preferably preheats the higher-opacity CD layer without significantly heating the lower-opacity main fuel. This enhances cryogenic shell stability without compromising the fuel adiabat.

IV. CONCLUSIONS

Ignition target designs rely on low-adiabat, high-areal-density fuel compression. A series of implosions with 92–95- μm -thick cryogenic D₂ layers was performed on OMEGA to study the physics of ignition-relevant, low-adiabat fuel assembly using the direct-drive configuration. The main sources of the adiabat degradation, observed in

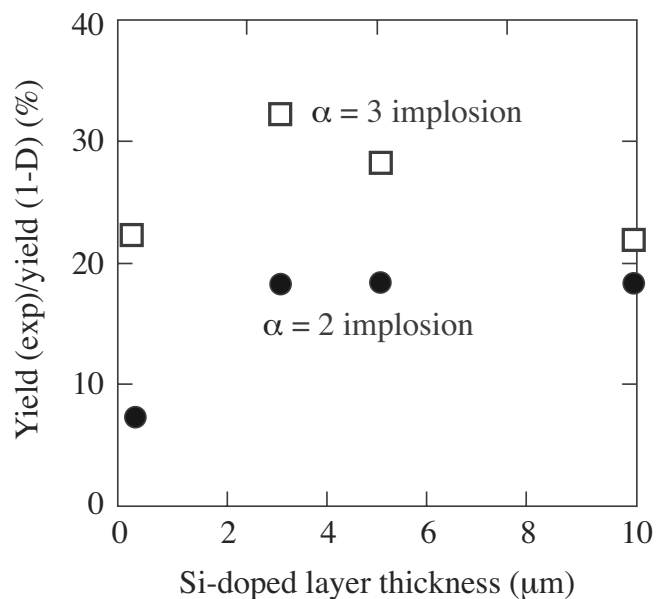


FIG. 10. Ratio of the experimental yield and the predicted yield for warm plastic implosions with different Si-doped layer thicknesses.

earlier experiments,^{6,7} were attributed to (1) shock mistiming resulting from inaccuracies in the laser-absorption modeling, (2) suprathermal-electron preheat generated by the two-plasmon-decay instability, and (3) under-sampling of higher ρR in the shell due to burn truncation. To increase the calculation accuracy, a nonlocal transport model was implemented in the 1D hydrocode LILAC. High cryogenic areal density with $(\rho R) > 200 \text{ mg/cm}^2$ was measured in the experiments¹¹ when the shock timing was optimized using the nonlocal treatment of the heat transport and the suprathermal-electron preheat source was mitigated.

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